



Biarri
COMMERCIAL MATHEMATICS

LAZY CONSTRAINTS

FOR FUN AND PROFIT

BAM 2016 – DR MICHAEL FORBES, ROBBIE PEARCE ET AL. THE UNIVERSITY OF QUEENSLAND

AGENDA

Solving tough MIP's

Branch and Price

Lazy Constraints

Fun

Profit

Benders Decomposition

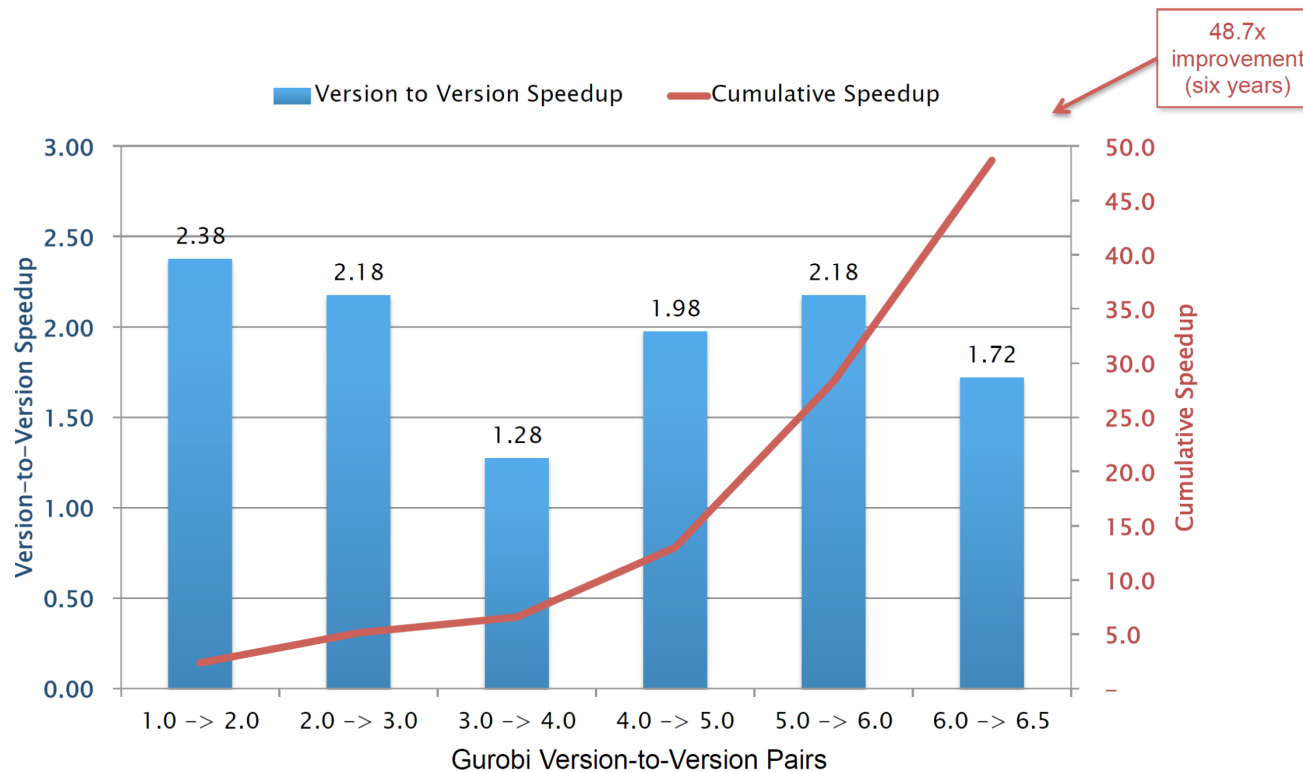
Framework

Why we should persevere with a MIP approach to optimisation problems

- You get a bound on solution quality
- It makes you think about modelling the problem
- Someone else is dedicated to making your problem run faster
- Many ways to make MIPs faster
- Many MIP based heuristics.

Someone else is dedicated to making your problem run faster

Gurobi Keeps Getting Better



1) Gurobi's Benchmark.pdf



Many ways to make MIP faster

- Better modelling
- Lagrangian Relaxation
- Branch and Price
 - Branch, Price and Cut
- Lazy Constraints

Branch and Price

- Reformulate the problem using some form of “composite” variable.
- At any LP relaxation, attempt to find variables which will improve the relaxation.
- Whenever we can't find any, and the solution is not integer, branch (or cut).

1) Branch-and-Price: Column Generation for Solving Huge Integer Programs: Barnhart, Johnson, Nemhauser, Savelsbergh and Vance, 1996

Branch and Price

PROS

- Often a tighter LP relaxation
- Often reduced symmetry
- Separation into master and sub problems:
 - additional non-linear constraints in the sub-problem.
- Sometimes it's the only way to solve the problem.

CONS

- Limited models where it is useful.
- Slow convergence of master problem.
- Tricks required for dual variable stabilisation.
- Not (yet) directly supported by modern IP solvers.

Cuts

- MIP Solvers use Branch and Cut
 - Mysterious (proprietary) pre-processing phase first
- Solve LP relaxation
- If not integer feasible, try to add a cut:
 - An equality satisfied by any feasible integer solution but not satisfied by the current relaxed solution
- If it is too much work/not useful enough to find a cut, then branch
- “Users” (i.e. the modeller) can also add cuts on the fly

1) Outline of an algorithm for integer solutions to linear programs. Gomory (1958)

Lazy Constraints

- Inequalities that cut off integer solutions
- Idea has existed for many years – e.g. Concorde TSP solver
- Often referred to as Branch and Cut (somewhat confusingly)
- Direct support by MIP packages has opened up many more options
 - Gurobi 5.0, May 2012
 - CPLEX?

TSP with Lazy Constraints

$$\min \sum_{ij} c_{ij} x_{ij}$$

Subject to:

$$\sum_i x_{ij} = 1 \quad \forall j$$

$$\sum_i x_{ji} = 1 \quad \forall j$$

$$\sum_{i \in S, j \in S} x_{ij} \leq |S| - 1 \quad \forall \text{ subsets } S$$

Lazy Constraints

PROS

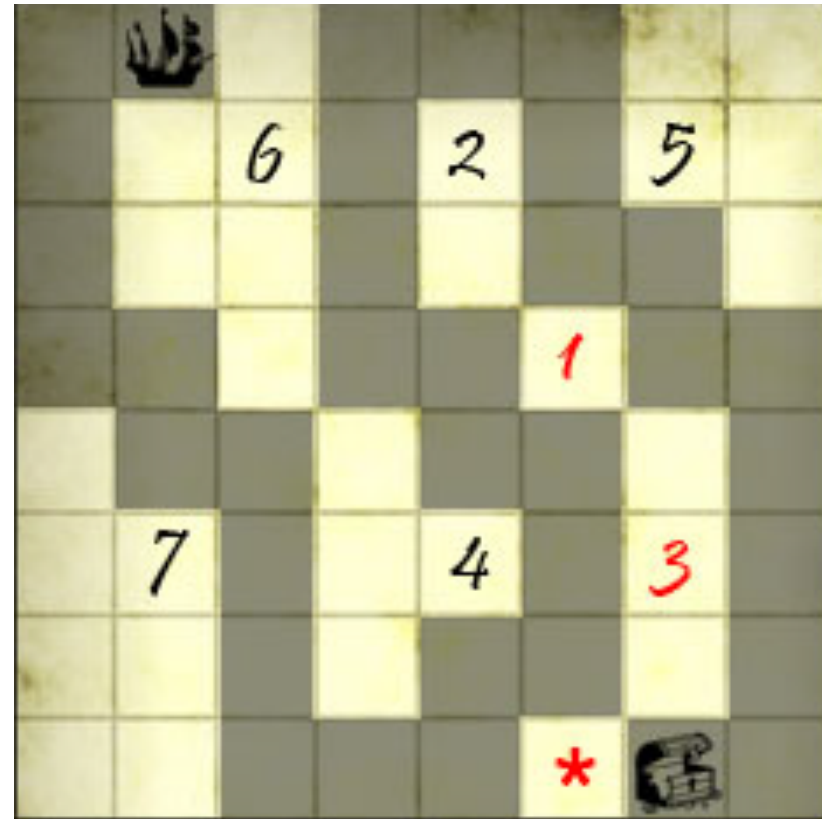
- Sometimes the only way to model the problem
- Much smaller models = much faster solve times
 - Optimistically assume constraints will be satisfied, add when not.
 - Optimistically estimate some component of the objective function and add constraints to improve our estimate.
- All the advantages of being embedded in a modern IP solver
 - multi-threading, heuristics, cuts, pre-solve, etc.

CONS

- Limited models where it is useful
- Can require too many lazy constraints

Sometimes the only way to model the problem

- Pieces of 8
 - $x_{ijk} = 1$ if square (i,j) is type k
 - Each square is used once
 - Squares of type 0 have exactly 2 neighbours of type 0 (except origin and destination have 1)
 - The right number of squares for each piece of 8
 - Pieces of different types aren't neighbours
 - At least one neighbour of the same type
- Plus ...
 - Each piece of 8 is connected
 - There are no loops in the path.



Sometimes the only way to model the problem

- Fillomino
 - $x_{ijk} = 1$ if square (i,j) is type k
 - Each square is used once
- Plus ...
 - Each “n-omino” has the correct number of pieces

- Can do this one with composite variables
No 8th piece of unknown size

	1		1					6		1		1	3	
3		7			1			4						
	1	6			6	1	4	4	1		1	8	1	
1		1		6				8				9	5	
			1				8							
	6				5		1	5	5	1	3	3		1
	4	5			1	3		5				1		
1		1		1		1					1			
				3	2		4		5	6		1	9	
1	7	1			1		4			5	1			1

3	1	7	1	7	7	6	6	6	6	8	1	8	1	3
3	7	7	7	7	1	6	6	4	4	8	8	8	8	3
3	1	6	6	6	6	1	4	4	1	8	1	8	1	3
1	6	1	6	6	8	8	8	8	9	9	9	9	5	5
4	6	6	1	8	8	8	8	9	9	9	9	9	5	5
4	6	6	6	5	5	3	1	5	5	1	3	3	5	1
4	4	5	5	5	1	3	3	5	5	5	3	1	9	9
1	7	1	7	1	2	1	6	6	6	6	1	9	9	9
7	7	7	7	3	2	4	4	5	5	6	6	1	9	9
1	7	1	3	3	1	4	4	5	5	5	1	9	9	1

1) Fillomino, Pearce and Forbes, Submitted April 2016

Optimistically assume constraints will be satisfied



1) Optimizing Network Designs for the World's Largest Broadband Project. Ferris, Forbes, Forbes, Forbes and Kennedy, Interfaces, 2015

Capacitated Spanning Tree Partition

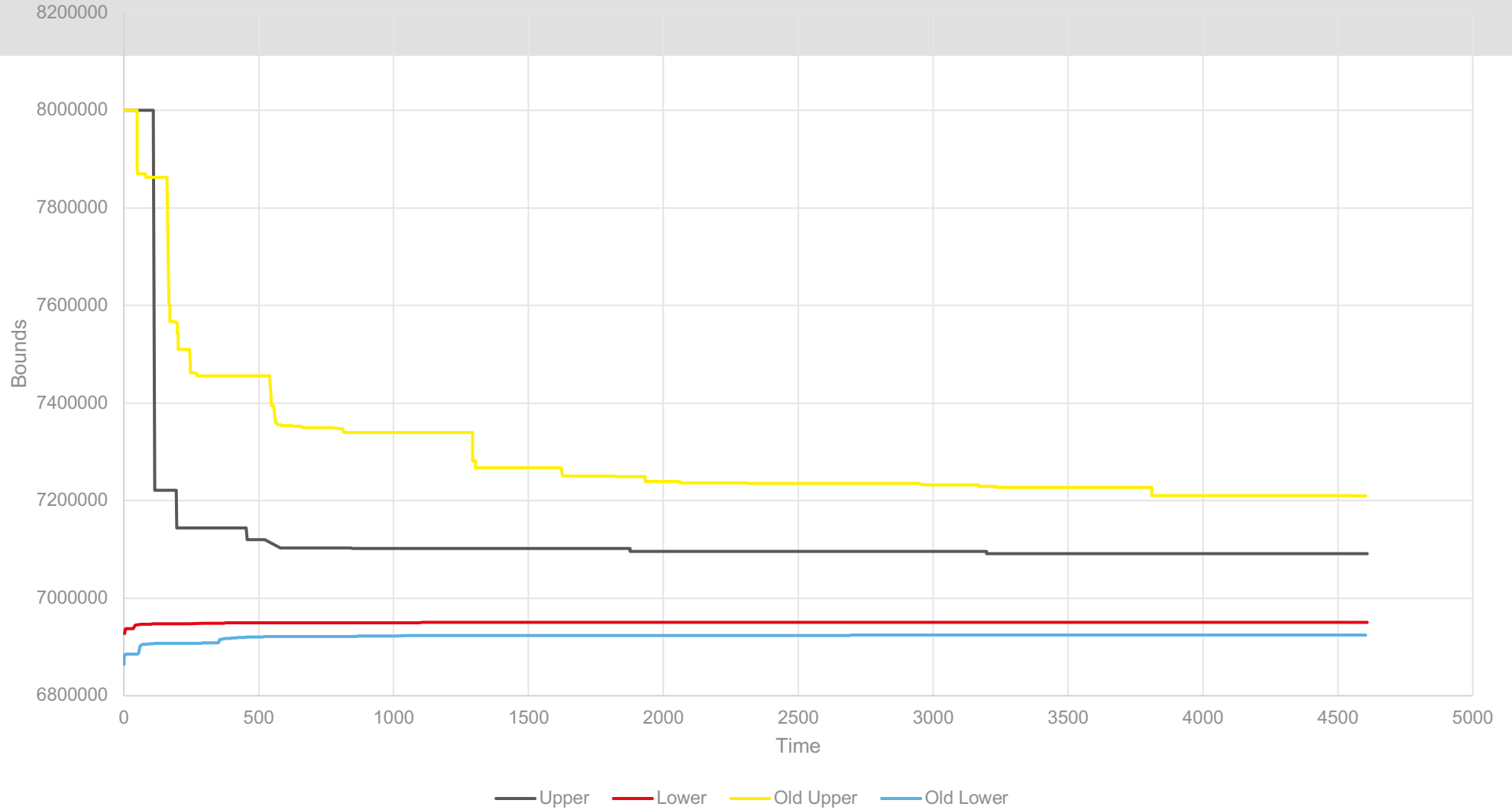
Direct IP Formulation

z_i	1 if node i is a hub
y_a	1 if directional arc a is used in the solution
x_a	“Units of demand” flowing on a
	Minimise cost of hubs and arc costs

Lazy IP Formulation

w_i	1 if non demand node i is used in the solution
y_a	1 if non-directional a is used in the solution
	Number of hubs is (number of nodes used – number of arcs used)
	Lazily eliminate problems

New vs Old



Pickup and Delivery Vehicle Routing

- Vehicle capacity and travel times
- Orders
 - Pickup and delivery locations
 - Pickup and delivery time window
- New approach combines composite variables and lazy constraints
- Composite Variable – Order String
 - Series of pickups and deliveries so that the vehicle starts and ends empty
 - Variables handle precedence (pickup before delivery), capacity and time windows
- Master problem sequences strings
 - Each order covered
 - Flow conservation through strings
 - Pairwise string connections legal
 - Longer string connections may be illegal – even cycles: Lazy Constraints

GUFLNDP

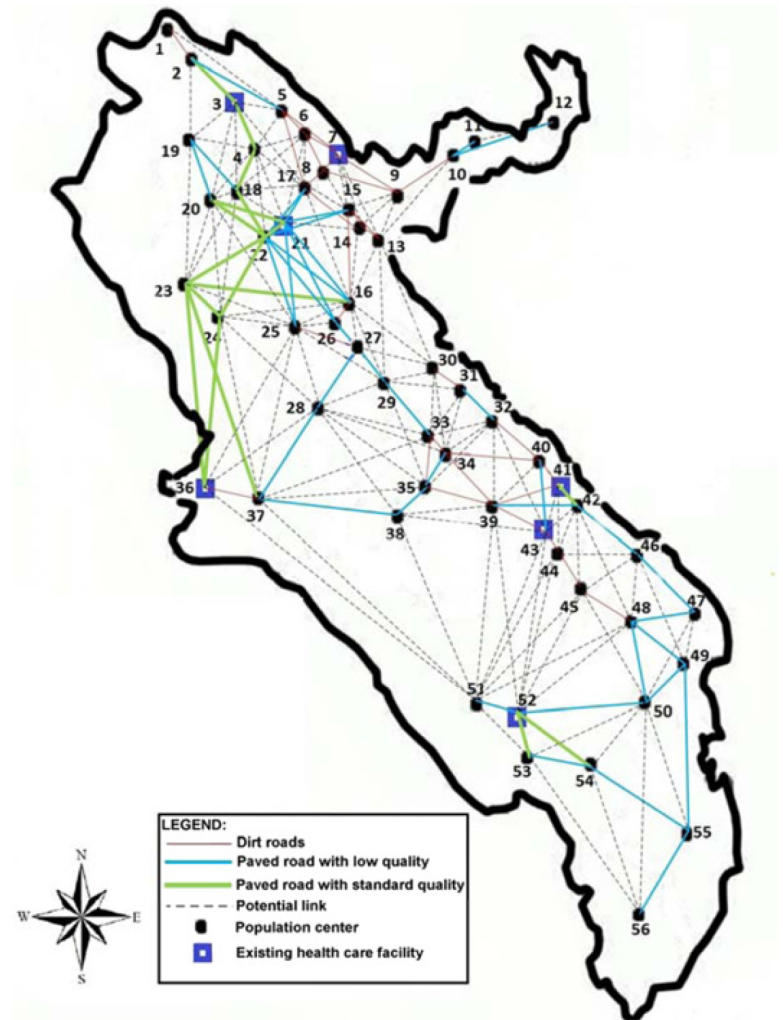
- **General Uncapacitated Facility Location and Network Design Problem**
- Nodes, Arcs, Facilities (a subset of nodes) N, A, F
- Cost of opening each facility (0 means already open)
- Cost of opening each arc (0 means already open)
- Cost per unit of movements on arcs
- Set of requests, each of which has a known volume, origin, candidate facilities (a subset of F)
- Any other constraints on the network structure.

1) UFL – many references

2) Modeling the budget-constrained dynamic uncapacitated facility location–network design problem ... Ghaderi et al, 2013

3) An improved Benders decomposition algorithm for the tree of hubs location problem, Martin de Sa et al, 2013

4) Benders Decomposition for the Design of a Hub and Shuttle Public Transit System, Maheo et al, 2015



GUFLNDP and Benders Decomposition

- z variables open and close nodes
- y variables open and close arcs
- Usual Benders Cut: $\theta_r \geq \theta^* - \sum \gamma_i z_i - \sum \lambda_{ij} y_{ij}$.
 - Cost for request r is greater equal to current cost (solving sub-problem) minus saving for opening candidate facilities minus saving for opening closed arcs
 - Can solve flow problem for each resource and use dual variables on node and arc constraints
- Solve sub-problem and use dual variables form appropriate constraints

Pareto-optimality

- An undominated cut is said to be Pareto-Optimal
- Magnanti and Wong core point method has been popular – but it is slow to compute this
- “Natural Benders Cut” for GUFLNDP
 - Solve shortest path tree from origin to nearest open facility
 - All dual variables for open facilities and arcs set to zero
 - Dual variables for node i set to $\max(\theta^* - dist_i, d_i^*)$ where $dist_i$ is the shortest distance from the origin to node i and d_i^* is the shortest possible distance from node i to any candidate facility for the current resource, if all arcs were opened.
 - Dual variables for unopened arcs set to satisfy the duality conditions:

$$\lambda_{ij} = \max(0, \gamma_i - \gamma_j - c_{ij})$$

1) Accelerating Benders Decomposition: Algorithmic Enhancement and Model Selection Criteria, Magnanti and Wong, 1981

Pareto-optimality

- The Natural Cut:
 - Is dual feasible
 - Has the same objective value as the primal optimal
 - Therefore it is primal optimal and is a valid Benders Cut
- Proving Pareto-Optimality of the Natural Cut
 - Carefully select solutions where the cut is binding (equals optimal solution of sub-problem)
 - Show that any cut that has equality at all these solutions is the natural cut
 - Therefore the cut can't be dominated
 - The only exception comes from connecting a resource to its closest candidate facility
 - Can solve this with a Balinski style cut (second closest candidate)

1. Integer programming: Methods, uses, computation. Balinski, 1965

2. Pareto-Optimality of the Balinski Cut for the Uncapacitated Facility Location Problem, Watson and Rogers, 2007

Benders Summary

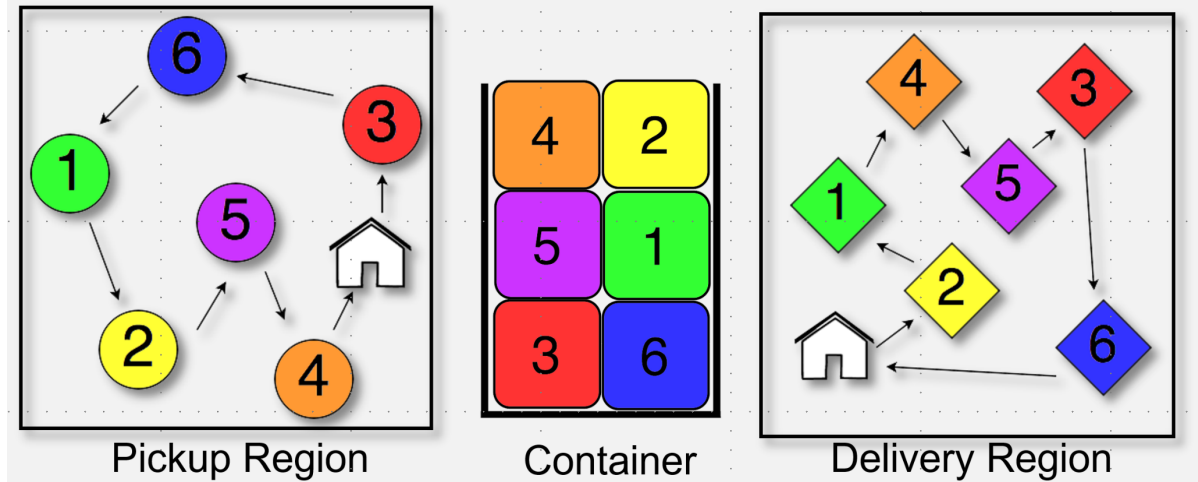
- Works well for problems which disaggregate (no shared capacity)
- Avoid feasibility cuts
- Warm start usually helps
- Pareto Optimal cuts important
 - Often naturally achievable
- Heuristics important
- Open issues
 - Natural warm start
 - Warm start in callback
 - Level of disaggregation
 - Natural second best cut is also pareto-optimal – which is best?

- 1) Disaggregated Benders Decomposition for solving a Network Maintenance Scheduling Problem, Pearce and Forbes, 2016
- 2) Several more papers to appear. Pearce et al, 2016



Other Applications

- Pickup and delivery TSP
 - Multiple Stacks
 - Solve two TSPs
 - Add lazy constraints if not stack feasible
 - Tightness of constraints!



- Power flow models
 - Many quadratic components in objective (per arc, wire type, time period)
 - Approximate with “natural” cut: $\theta_{ijwt} \geq x_{ijwt}^{*2} + 2x_{ijwt}^*(x_{ijwt} - x_{ijwt}^*)$
- Crane movements
 - Lower bound IP ignoring clash constraints
 - In call back, resolve clash constraints (another IP) to get upper bound and cut off all similar solutions

Conclusions

- Solve the model you want to solve
 - Especially if there is a big gap from “structure” to full detail
- Can you approximate the objective function and leave out detail?
- Is there a natural way to refine an approximation / improve feasibility?
- Tightness of cuts is important
 - Lift LHS, tighten RHS
- Become an expert in your modelling environment
 - Fast prototyping, especially of Callbacks
- Questions?